

Demo of VisionFT: A Multimodal Tactile Sensor for Manipulation Pl: Mark Cutkosky

TOYOTA
RESEARCH INSTITUTE

Biomimetics & Dexterous
Manipulation Laboratory



Students: Julia Di, Hojung Choi, Seongheon Hong

(Custom 6-axis F/T Sensor)

VisionFT: A multimodal tactile sensor combining vision and capacitive F/T sensing for dexterous manipulation.

